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Motivation & Problem

- A NLP system usually solves multiple tasks;
- Some of these tasks are highly inter-dependent.

✓ We focus on three tasks for **Entity Analysis**



Properties

- Each task predict a structural output;
- Task dependency has **no ordering**.

Challenges

- How to exploit their interdependencies?
- How to control the error propagation?
- How to reduce the inference time complexity?

Tasks Introduction

He left [Columbia] in 1983 with a BA degree, ...
after graduating from [Columbia University] he
worked as a community organizer in Chicago ...

Coreference:

$y_i = \{1, 2 \dots i\}$ $y_{\text{coref}} = (\text{Columbia}, \text{Columbia University})$

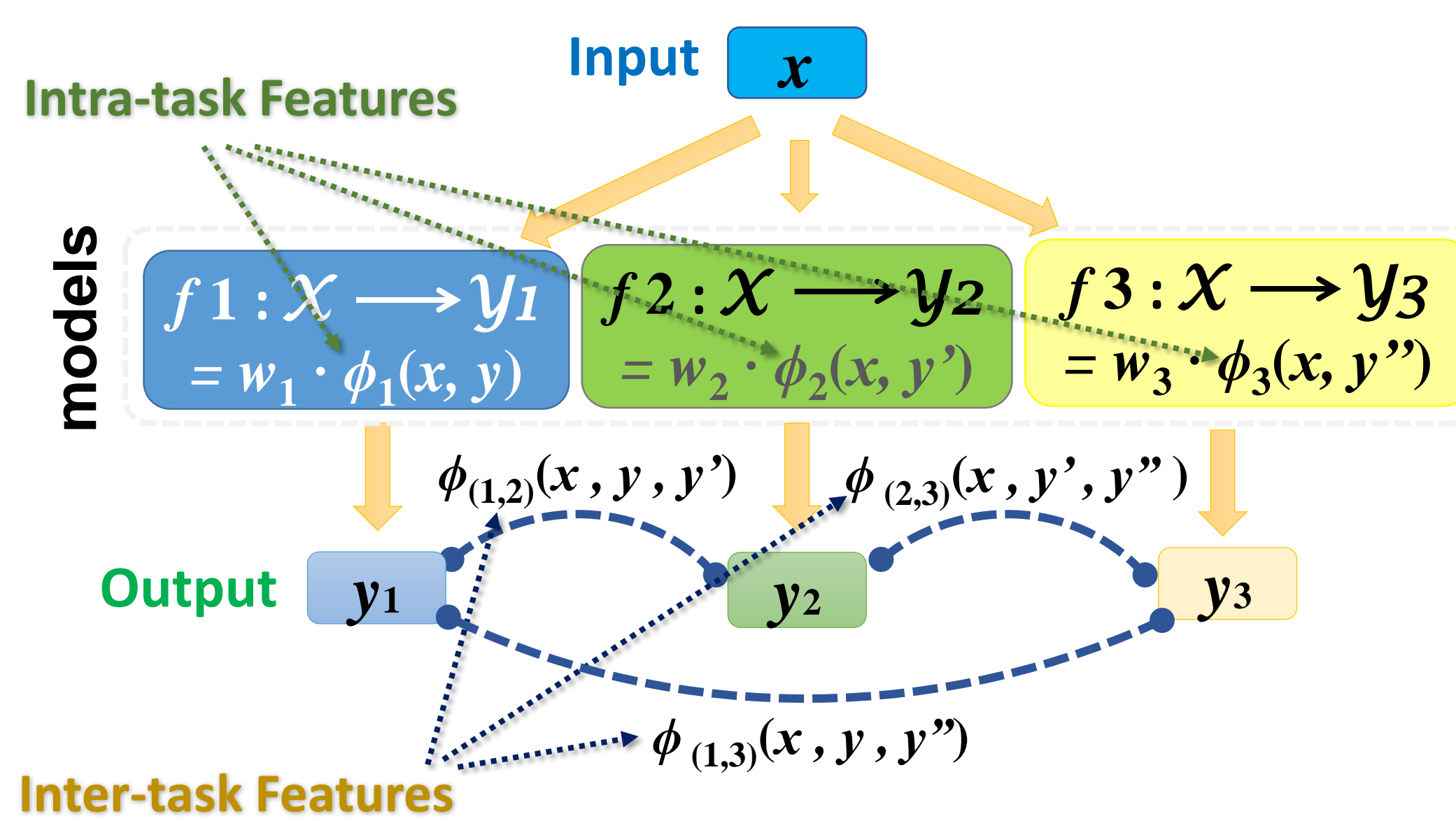
Named Entity Recognition:

$y_{\text{ner}} = (\text{ORG}, \text{ORG})$
 $y_i = \{\text{ORG, PER, GPE, LOC, FAC, VEL, WEA}\}$

Entity Linking:

$y_{\text{link}} = (\text{Columbia_University}, \text{Columbia_University})$
 $y_i = \{\text{Columbia_University, Columbia_District, Columbia_College, Columbia_University}\}$

Multi-Task Structured Prediction



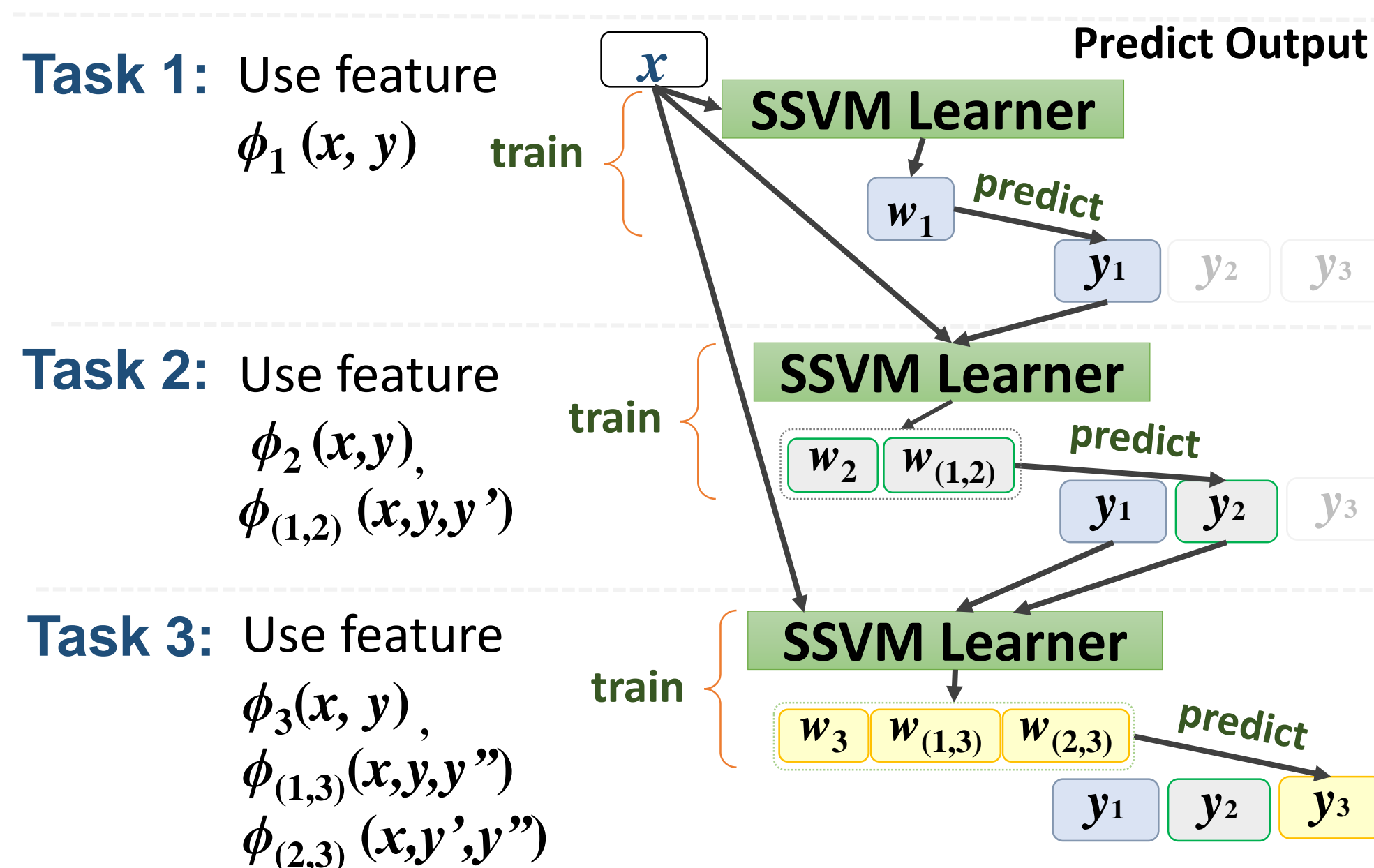
interdependencies between tasks are captured by the inter-task features.

Inter-task Features for Entity Analysis

- Coref-NER:** e.g.: Agreement of NER tags of two coreferent mentions
ORG == ORG
- Coref-Link:** e.g.: Relation of KB entries of two coreferent mentions
University is-same-category University
Mathematics is-sub-category Mathematics education
- NER-Link:** e.g.: NER-tag and Category pair indicator
(ORG, University) Bonus to the co-related pair
(ORG, Institute)
(PER, President) ...

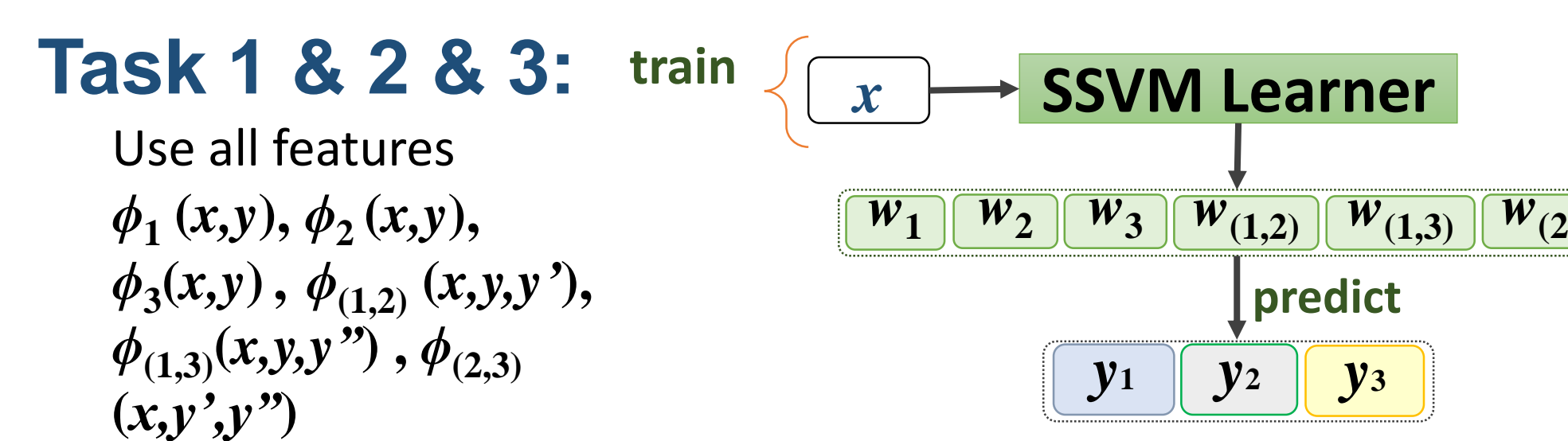
MTSP Architectures

Pipeline Architecture



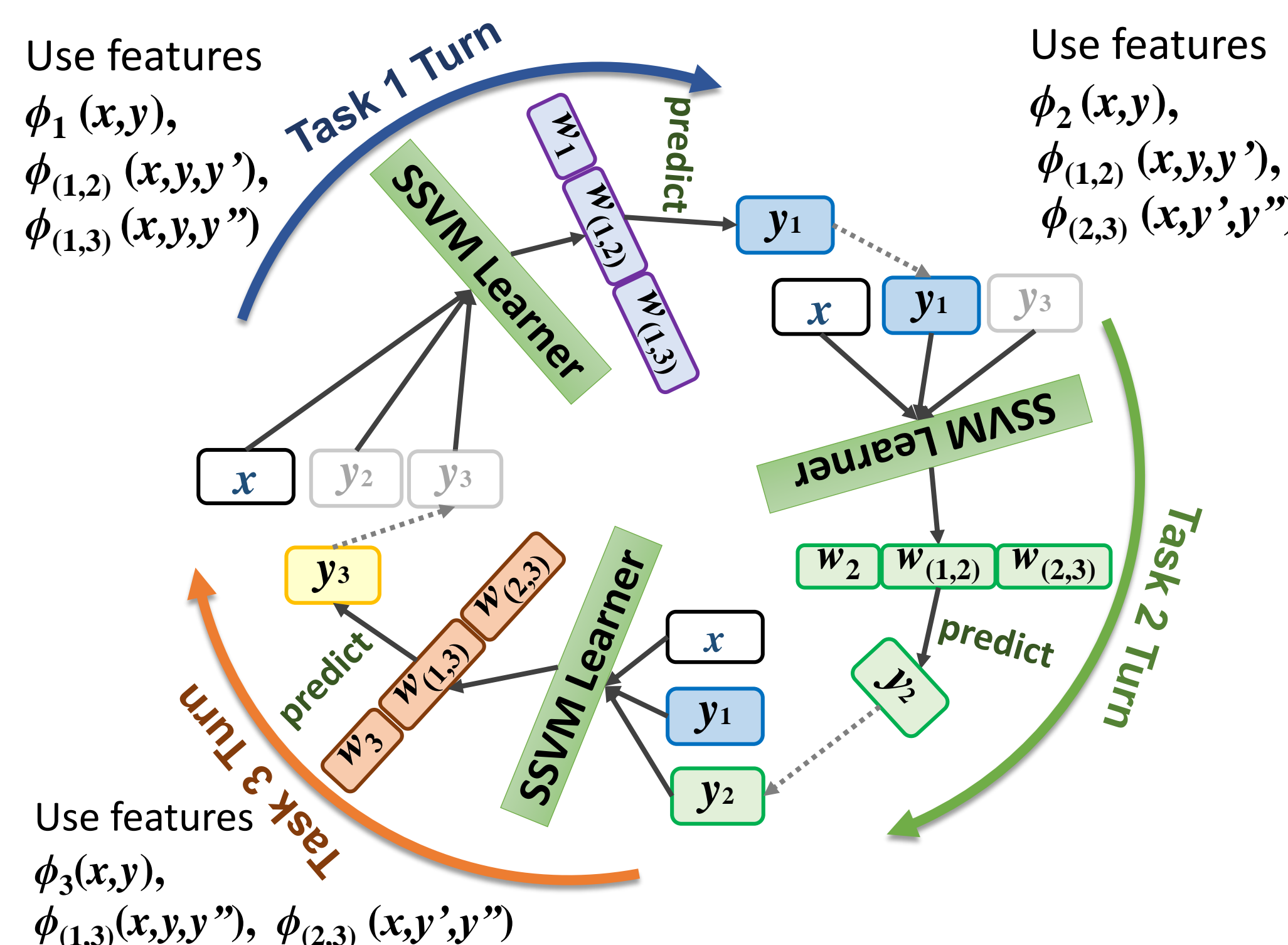
Learning $k (= 3)$ independent models, one after another.

Joint Architecture



Cyclic Architecture

Step 1: Define a order: Task 1 → Task 2 → Task 3
Step 2: Predict initial outputs: y_1, y_2, y_3



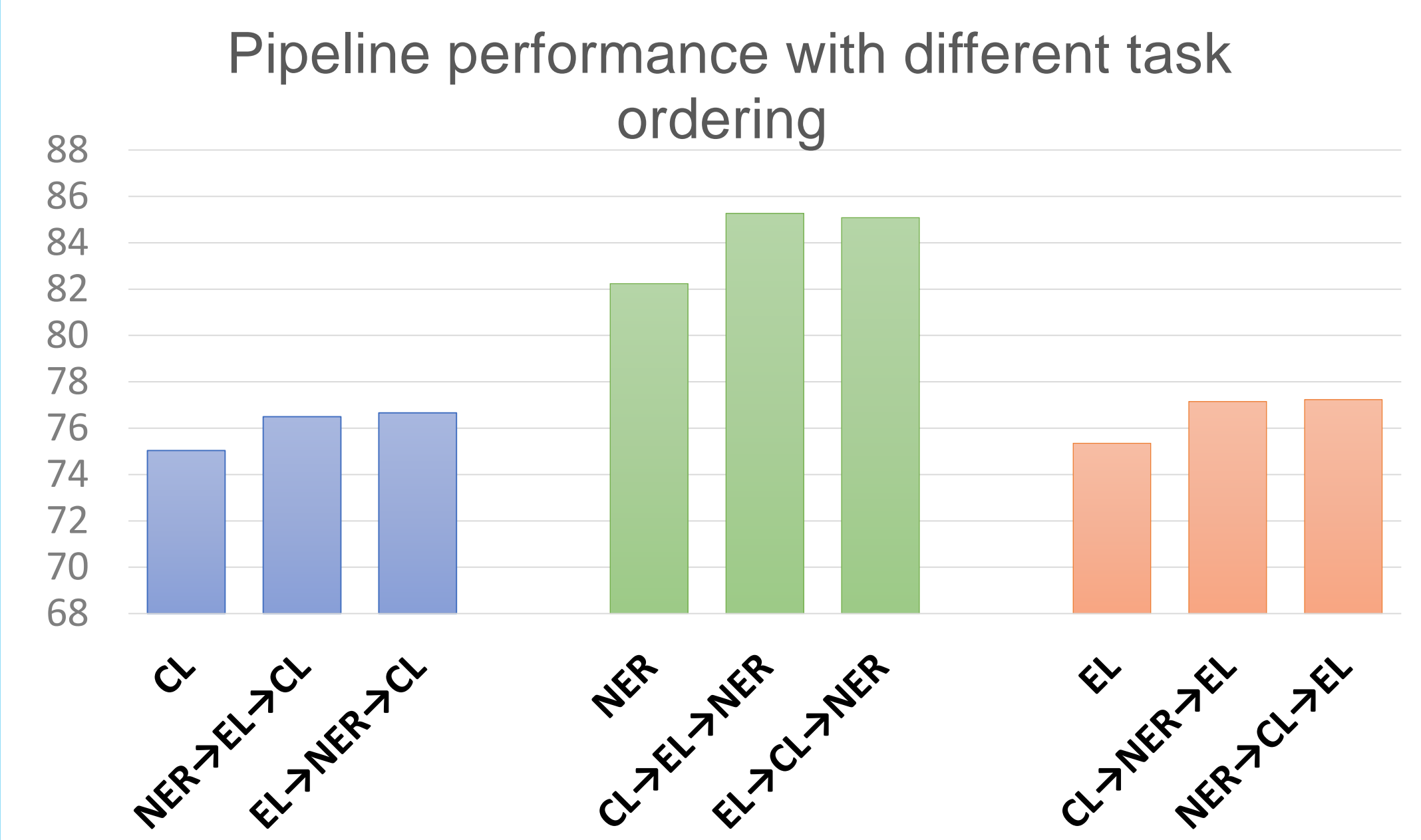
Experimental Results

Experimental Setups

- Corpora: ACE 2005 (338/144/117 docs), TAC-KBP 2015 (132/36/167 docs)
- Knowledge Base: Wikipedia (2014), Freebase (2015)
- Evaluation: Coref. CoNLL, NER Hamming, Link. Hamming; Cross-Coref. CEAFm & NER Link. NERLC

✓ All metrics are accuracies, the larger the better

Pipeline Architecture Performance



- Each group of bars represents one task. In each group, we show the accuracy when the task is placed at first (1st bar), or at last (2nd and 3rd bar).

- The task performs better when it is placed last in order.
- There is no ordering that allows the pipeline to reach peak performance on all the three tasks.

Joint & Cyclic Architecture Performance

ACE05 Test Set Performance

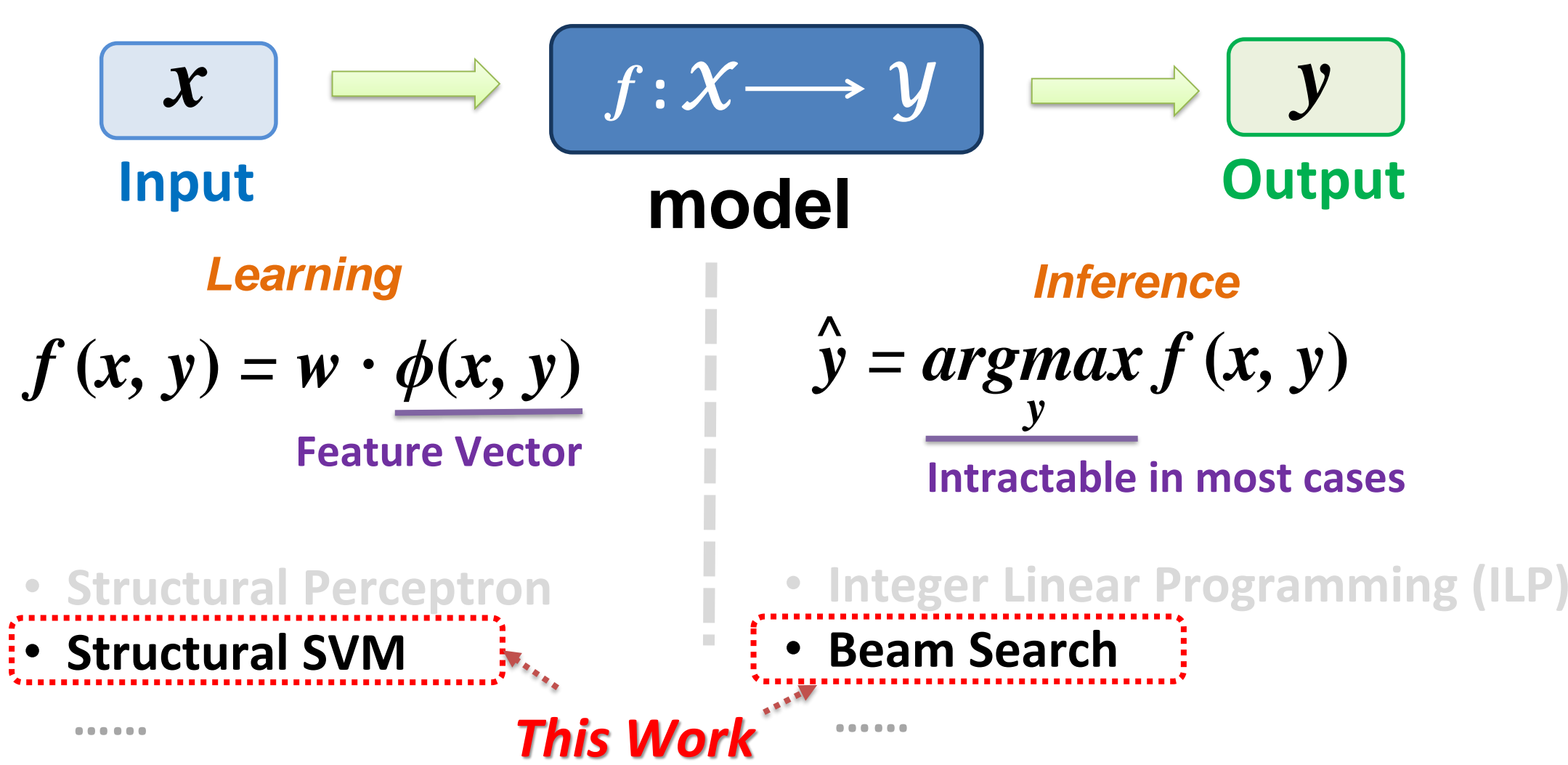
| Algorithms. | Coref | NER | Link | Train time |
|---|-------|-------|-------|------------|
| | CoNLL | Accu. | Accu. | Min. |
| Berkeley | 76.35 | 85.60 | 76.78 | 31min |
| a. Results of Joint Architecture without Pruning | | | | |
| STSP | 75.04 | 82.24 | 75.36 | 9min |
| Joint w. Rand Init | 75.35 | 82.20 | 76.99 | 48min |
| Joint w. Good init | 77.58 | 85.71 | 78.77 | 34min |
| b. Results of Joint Architecture with Pruning | | | | |
| Score-agnostic | 77.07 | 85.63 | 78.71 | 16min |
| Score-sensitive | 77.85 | 87.18 | 80.28 | 37min |
| c. Results of Cyclic Architecture | | | | |
| Unshrd-Wt-Cyclic | 77.29 | 84.18 | 80.67 | 11min |
| Shared-Wt-Cyclic | 76.53 | 82.16 | 79.60 | 10min |

- Joint-Good-Init > STSP Interdependency, captured by inter-task features, does benefit the system.
- Joint-Good-Init > Joint-Rand-Init Search-based inference for large SP problems suffers from local optima and can be mitigated by a good initialization.
- Search-based MTSP is competitive or better than the state-of-the-art systems.
- Score-sensitive pruning further improves the joint architecture. While score-agnostic pruning brings around 2 times speed up.
- Unshared-Weight-Cyclic performs better than Shared-Weight-Cyclic, but neither of them are sensitive to the task ordering.

Conclusions

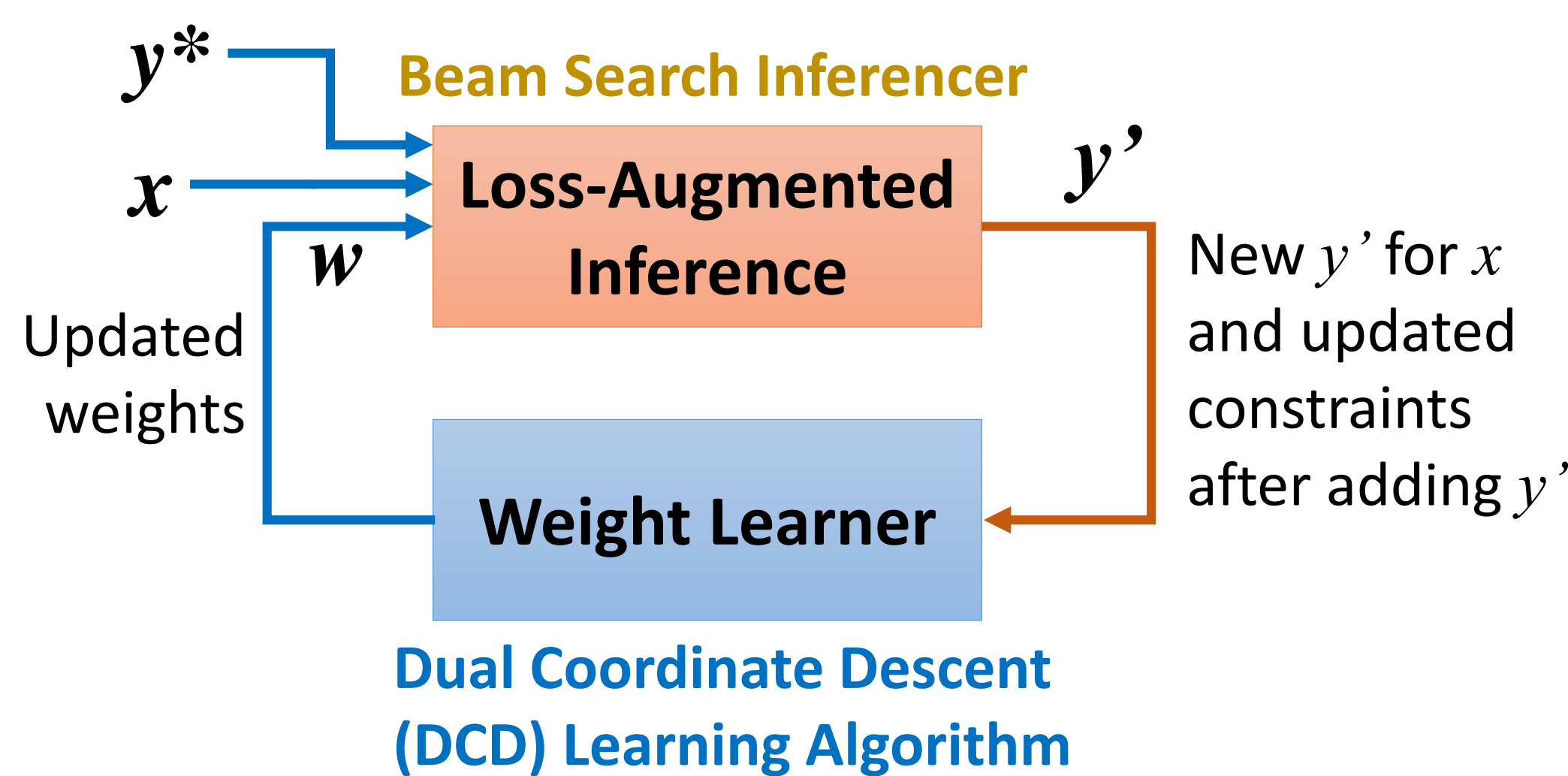
- Formulated the problem of multi-task structured prediction (MTSP) for entity analysis.
- Applied the search-based learning framework, where structured SVM is employed for training and beam search for inference.
- Develop the cyclic architecture that performs as good as joint architecture, but with a much faster speed.

Single-Task Structured Prediction



SSVM Learning with Search-Based Inference

Structured SVM Learning Framework



Three main advantages of search based inference

- Inference time complexity is not sensitive to the feature complexity;
This is fairly important in MTSP when using inter-task features, especially higher order features.
- Can optimize any arbitrary non-decomposable losses;
When doing loss-augmented inference in structured SVM:
 - Task specific losses, e.g., coreference CoNLL score;
 - (Weighted) task compatibility losses, TAC-KBP NERLC score;
- Can apply pruning to control the inference speed;
For example, ILP inference usually uses a blackbox solver, which is not flexible to apply pruning.