



Amortized Inference and Learning

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Randomized Greedy Search for Structured Prediction:

Structured Prediction

Amortized RGS Inference and Learning

Given: a set of structured input-output pairs of the form (x, y)

Handwriting recognition

x =

y = structured

Image labeling





\Box **RGS**(α) Inference Solver

- \uparrow α fraction of the output variables are initialized with a learned IID classifier and remaining $1 - \alpha$ variable randomly. Prior work is a special case with $\alpha = 0$ [Zhang et al., 2014, 2015]
- \uparrow α controls the trade-off between the minimum depth at which target outputs can be located and diversity of starting outputs
- \wedge Non-zero α will potentially help with large structured outputs

Learning for Amortized Inference

- **Learn:** a function $F : X \rightarrow Y$ to make predictions on new inputs
- **Evaluation:** against a loss function $L(x, y, F(x)) \in \mathbb{R}^+$
 - ▲ Hamming loss, F1 score, B³ score ...

Key Challenge: "Argmax" inference

Popular Approaches: CRFs, Structured SVM ...

- Learn parameters of linear models
- $\phi(x, y)$ is n-dim feature vector over input-output pairs
- *w* is n-dim parameter vector

```
F(x) = \arg \max w \cdot \phi(x, y)
```

G "Argmax" inference:

Y is generally exponentially large

Find the max. scoring output in an exponentially large set of possible outputs. Computationally hard (NP-hard) for all but simplest dependency structure of features $\phi(x, y)$

- - Given a set of structured inputs D_x and scoring function F(x, y) to score candidate outputs, we want to reduce the number of iterations of RGS(α) to uncover high-scoring structured outputs
 - <u>Key Idea:</u> Learn evaluation function E(x, y) to select good starting states to improve the accuracy of greedy search guided by F(x, y)[Boyan and Moore, 1997]



Optimizing "non-decomposable" loss functions is hard

Requires a loss-augmented inference solver, which is tractable only for decomposable loss functions

Training and Inference is expensive for complex models

- Typically, inference is performed *independently* for each structured input – No reuse of knowledge.
- Repeated calls to inference solver during training of weights

Speedup Learning meets Structured Prediction

- Speedup learning methods improve the efficiency of problem-solving process via practice on training problems
- If we abstract out inference solvers as computational search processes, we can learn search control knowledge to improve the efficiency of inference. Study this general idea in the context of randomized greedy search (RGS).
- RGS (multiple iterations of greedy search from random outputs) requires many iterations to achieve high accuracy

Experimental Results

RGS with best α gives better accuracy than RGS(0) for tasks with large structured outputs. $RGS(\alpha)$ is competitive or better than many state-ofthe-art methods. **b.** Image Segmentation (MSRC21)

					Global	Average	
a. Coreference Resolution (ACE2005)					ICCV2011	85	77
	MUC	BCube	CEAFe	CoNLL	CRF-CNN	91.1	90.5
Berkeley	/ 81.41	74.70	72.93	76.35	RGS(0)	81.27	73.14
RGS(0)	80.07	74.13	71.25	75.15	RGS(α)	85.29	78.92
RGS(α)	82.18	76.57	74.01	77.58	RGS(α)-CNN	91.53	90.28

\Box Prediction and generation accuracy of RGS(α) on development set



0.84 0.82 0.80.78

Prediction -

Generation

0.76

MSRC-21

Inference and training time improves significantly with amortized RGS

and doesn't work very well for large structured outputs.

Amortized RGS: Learn evaluation function to select good

starting states to improve the accuracy of greedy search

(high accuracy with a small number of RGS iterations)

Plug amortized RGS inference solver in the inner-loop of

structured learning to improve the efficiency of training

Testing Time (milli seconds)					Training Time (minutes)						
	Bibtex	Bkmrks	HWLrg	MSRC	ACE05		Bibtex	Bkmrks	HWLrg	MSRC	ACE05
SPEN	5791	63073	-	-	-	SPEN	114	237	-	-	-
DVN	18086	211448	-	-	-	DVN	20	204	-	-	-
RGS	69890	288058	17323	9451	282864	DCD(RGS)	95	392	71	115	171
A-RGS	20925	98921	4812	2294	55355	DCD(A-RGS)	32	319	44	27	39